

- You have 90 minutes to answer the questions.
 - Work on your own. Any form of communication will result in immediate disqualification.
 - To receive full score you have to justify your answers, unless indicated otherwise.
 - Exams with incomplete headers will not get evaluated.

1.	2.	3.	4.	5.	6.	7.	8.	9.	10.	11.	Σ
14	5	6	6	6	8	10	8	6	8	10	87
6	3	5	0	6	5	7	6	2	0	9	39.5

1. (14 pts) You are right next to a fountain. Given two water jugs of 5l and 3l respectively, you have to fill the 5l jug with 4l of water.

~~ans~~ (3 pts) Propose a good state representation and goal states in the chosen representation.

Start: minden übersta-

Start: minden ives start

b.) (6 pts) Define the actions (operators) that are meaningful in this state space. Give the rules of the state transition function for this state space using the following table in the form

$$(\{state_0\}, action) \rightarrow state_1,$$

where $\{state_0\}$ represents the set of states where the given *action* can be executed, and $state_1$ is the resulting state of the *action*. If you can use parameters to define input state set of the operator, you can also use it to define the resulting state.

c.) (2 pts) Propose a good state evaluation function for measuring proximity to the goal state.

d.) (3 pts) Perform hill climbing search without backtracking.

1

2. (5 pts) Compare A*, RBFS and SMA* in terms of memory usage and time requirement.

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- SMA*: simplified memory bounded A*: korlátosított memória, minden, mindenig kidobja, ha nem, mindenig kidobja, ha nem, mindenig kidobja, ha nem,
- RBFS: rövidítéses mivel mindenig előrelép a körül, ha a körül nem jó
- A*: memoriavezetéses, mivel tárolja a node-eket és nem dobja ki, ha nem kellenele

3.5 p

3. (6 pts) Consider a world with objects A, B, and C! We will look at a logical language with constant symbols X, Y, and Z, predicate symbols p , q , and r , and function symbol f . Consider the following interpretation!

$$\begin{aligned}I(X) &= \mathbf{B}, I(Y) = \mathbf{B}, I(Z) = \mathbf{A} \\I(f) &= \{\langle A,B \rangle, \langle B,C \rangle, \langle C,C \rangle\} \\I(p) &= \{\mathbf{A}, \mathbf{B}\} \\I(q) &= \{\mathbf{C}\} \\I(r) &= \{\langle B,A \rangle, \langle C,B \rangle, \langle C,C \rangle\}\end{aligned}$$

For each of the following sentences, decide whether it is true or false in the given interpretation!

a.) $r(f(Z), Z)$

b.) $g(f(f(f(Z))))$ nope

$$c.) \exists y f(y) = f(f(y))$$

d.) $\forall y \ r(f(y), y)$

2902

$$c.) \forall u, v r(u, v) \rightarrow (\forall w r(u, w) \rightarrow v = w)$$

harris, wins kit elyan
 negeleek ahol a mobodik
 evezet egyszerű ol. eset
 rigaz etel/ kutek

$$d.) \forall u, v r(u, v) \rightarrow (\forall w r(w, v) \rightarrow u = w)$$

rigaz

GB GC
 forditva

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 mobodik
 ol. eset
 etel/ kutek
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4. (6 pts) Show that the following sentences are equivalent by converting them to CNF.

$$\forall x [\forall y P(x, y)] \rightarrow Q(x)$$

$$\forall x \exists y [P(x, y) \rightarrow Q(x)]$$

$$\forall x \exists y [P(x, y) \rightarrow Q(x)] /$$

$$\forall x \exists y \neg P(x, y) \vee Q(x)$$

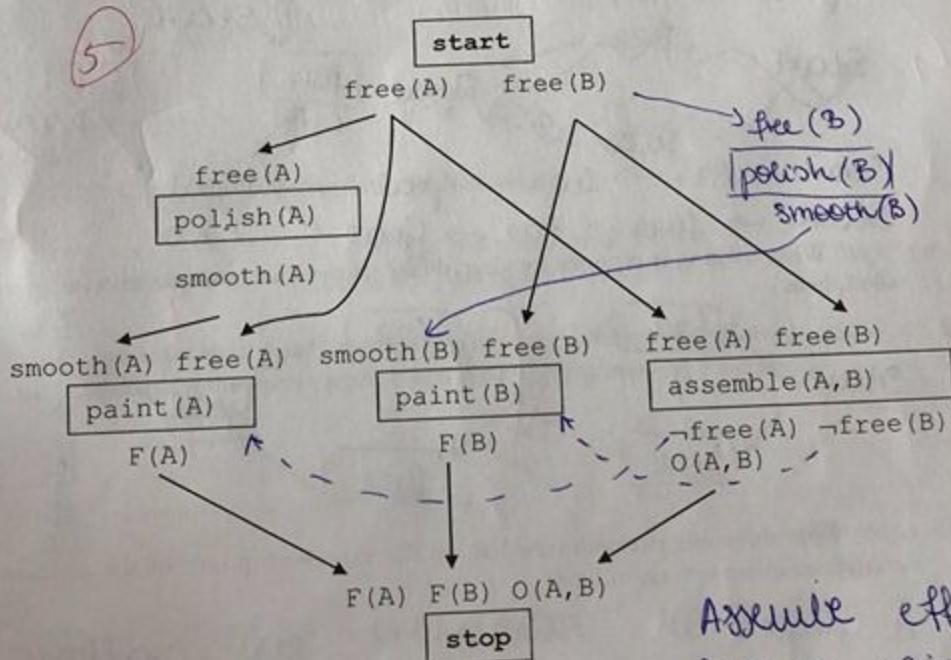
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$$\forall x \neg [\forall y P(x, y)] \vee Q(x)$$

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ekvivalens

5. (6 pts) Let us consider the following incomplete partially ordered plan. What steps are missing to complete the plan? Mark them in the graph.



Assume effektive törlheti a paint(A) és paint(B) prekondícióit

6. (8 pts) Consider the following expression returned by a situation calculus planner:

7

$\text{RESULT}(A, \text{RESULT}(F, \text{RESULT}(D, \text{RESULT}(Q, s))))$

- a.) (2 pts) What is the role of s_i in the expression?

So a kezdeti állapot, előző indukciói.

- b.) (2 pts) What is the total number of situations the agent meets when executing the plan? Justify your answer.

$$\begin{array}{ccccccc} \text{Ren}(Q, s_0) & \text{Ren}(D, s_1) & \text{Ren}(F, s_2) & \text{Ren}(A, s_3) & & & \\ \xrightarrow{s_0 \rightarrow s_1} & \xrightarrow{s_1 \rightarrow s_2} & \xrightarrow{s_2 \rightarrow s_3} & \xrightarrow{s_3 \rightarrow s_4} & & & \\ & & & & & & s_4 \end{array}$$

$$\text{kezdeti állapot + állapotok} \Rightarrow 1+4=5$$

- c.) (4 pts) Extract the plan in the form of a graph from the expression.

3

$$Q \rightarrow D \rightarrow F \rightarrow A$$

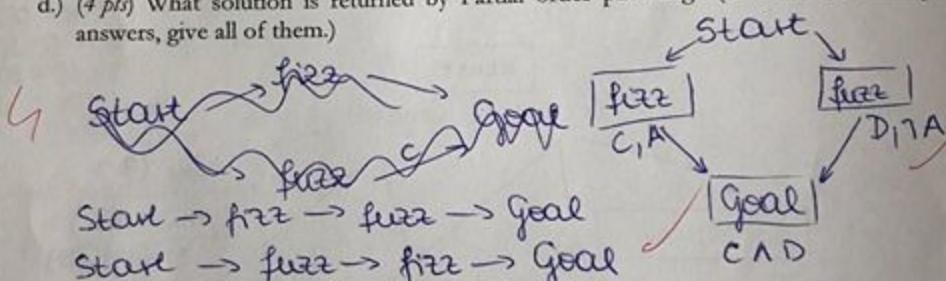
So $\xrightarrow{} \text{Result}(Q, s_0) \xrightarrow{} \text{Result}(D, \text{Result}(Q, s_0)) \xrightarrow{} \text{Result}(F, \dots)$

$$\downarrow \\ \text{Result}(A, \dots)$$

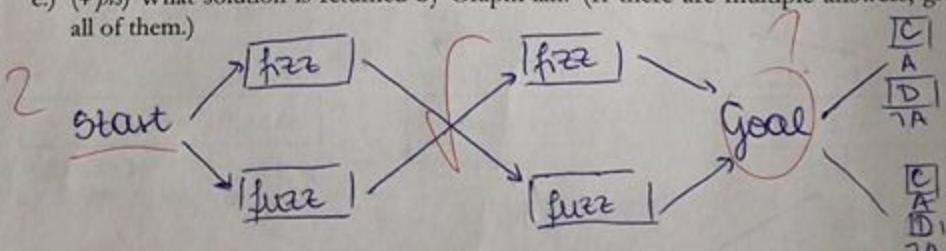
7. (10 pts) Consider the following domain with the goal $C \wedge D$.

Op.: **fizz** Precondition: - Effect: C, A
 Op.: **fuzz** Precondition: - Effect: $D, \neg A$

- d.) (4 pts) What solution is returned by Partial order planning? (If there are multiple answers, give all of them.)



- e.) (4 pts) What solution is returned by GraphPlan? (If there are multiple answers, give all of them.)



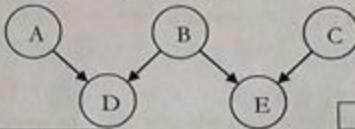
- f.) (2 pts) What does this example reveal about the expressive power of the solution descriptions in the two algorithms?

1 A GraphPlan szemlélteti egy grafban az összes lehetséges megoldást / itthonat

8. (8 pts) Consider the following Bayesian network:

(1)

$$P(A) = 0.2 \quad P(B) = 0.5 \quad P(C) = 0.8$$



	$P(D A, B)$
A, B	0.9
$\neg A, B$	0.6
A, $\neg B$	0.5
$\neg A, \neg B$	0.1

	$P(E B, C)$
B, C	0.2
$\neg B, C$	0.4
B, $\neg C$	0.8
$\neg B, \neg C$	0.3

(2)

a.) (4 pts) Suppose we know the value of D. Are A and B d-separated given D? Are A and E d-separated given D?

- A is d-separated, X
- A is d-separated ✓

b.) (4 pts) What is the probability of A being false, given that all other variables are true?

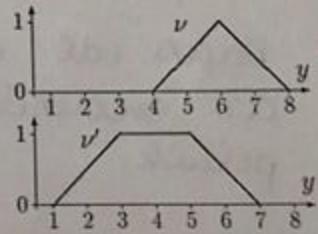
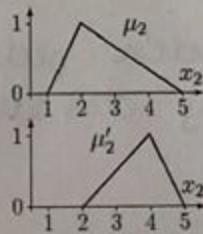
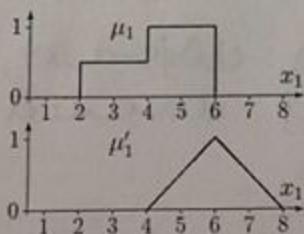
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9. (6 pts) Consider the following fuzzy sets and rules:

(R₁) If x_1 is μ_1 and x_2 is μ_2 , then y is ν .

(R₂) If x_1 is μ'_1 and x_2 is μ'_2 , then y is ν' .

where x_1 and x_2 are input fuzzy variables, y is the output fuzzy variable, and $\mu_1, \mu_2, \mu'_1, \mu'_2, \nu$, and ν' are predicates for the fuzzy variables with the following member functions:

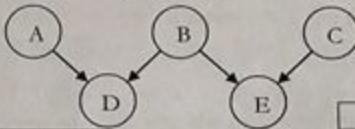


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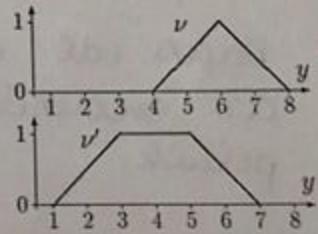
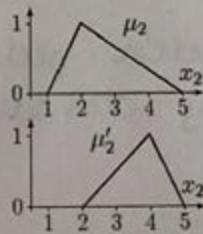
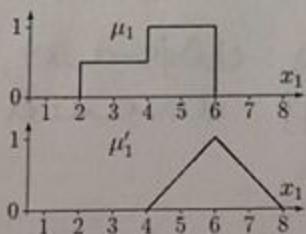
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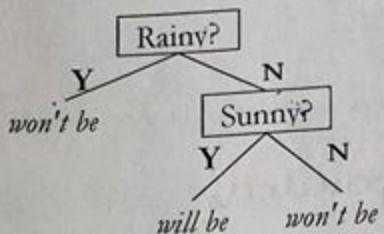


✓

Based on these fuzzy sets and the rules, what output μ_{out} does a controller with Mamdani implication return for the input tuple (5, 2.5)?

5

10. (8 pts) Let us consider the following decision tree and the associated data set.



#	Rainy	Sunny	Hot	Summer	Sunday	Picnic	FP	FN
1.	Y	N	N	N	N	won't be	X	
2.	N	Y	N	N	Y	will be	X	
3.	N	Y	Y	Y	Y	won't be		X
4.	N	Y	Y	N	Y	won't be		X
5.	Y	N	N	N	Y	won't be	X	
6.	N	Y	N	N	Y	won't be		X

inválid művek előírásai?

- a.) (3 pts) For each sample in the data set, indicate in the appropriate column if it is considered a false positive or a false negative with respect the answer given by the decision tree.

- b.) (5 pts) Which terminal leave would be worth substituting for an attribute test and why? (Rainy = Y, Sunny = Y, Sunny = N?) Which attribute would result in the largest gain?

Há az eső esetén mindenki elmarad a piknik.

Napok idő esetén pedig előfordult, hogy az esőmellett az, hogy elmarad a piknik.

11. (10 pts) Decide whether the following statements are true or false and justify your answer. 9

- Points are only given for the justification.
- a.) Admissible heuristics are by nature optimistic, because they think the cost of solving the problem is usually less than it actually is. Igaz
A heurisztika akkor elfogadható, ha nem
becsüli túl a kölcsönöt.
 - b.) Alpha-beta pruning can only alter the computed minimax value of the root of a game search tree if the order of the terminal nodes is inconsistent. Hamis X
Az alpha-beta metszésük változtatja a
megvizsgáltak körülötti arányt.
 - c.) If the premises are consistent, first-order resolution terminates without a contradiction.
Hamis, akkor kontradikció kell legyen.
 - d.) If first-order resolution terminates without a contradiction, the premises are consistent.
Hamis, a rezultátus végen az ellentmondás
jelenti, hogy igaz volt a következtetés.
 - e.) If A and B are independent, then A and B are conditionally independent given C. X

igaz,
meg tudunk
adni ilyen C-t.

